

## GENERALIZED METHOD OF MOMENTS

$z$  data generated by a process parameterized by a  $k \times 1$  vector  $\theta$ .

$l(z, \theta)$  log likelihood of  $z$ ,

$\theta_0$  true value of  $\theta$  in the population.

$g(z, \theta)$   $m \times 1$  vector of functions of  $z$  and  $\theta$  that have zero expectation in the population if and only if  $\theta$  equals  $\theta_0$ :

$$(1) \quad E g(z, \theta) \equiv \int g(z, \theta) \cdot e^{l(z, \theta_0)} dz = 0 \text{ iff } \theta = \theta_0.$$

The  $E g(z, \theta)$  are *generalized moments*, and the analogy principle suggests that an estimator of  $\theta_0$  can be obtained by solving for  $\theta$  that makes the sample analogs of the population moments small.

Example.  $z = (x, y)$ ,  $y = f(x, \theta_0) + \epsilon$ ,  $x \perp\!\!\!\perp \epsilon$

$$g(z, \theta) = P(x)'(y - f(x, \theta))$$

with  $P(x)$  a vector of polynomials in  $x$ .

Assume  $g(z, \theta_0)$  has a positive definite  $m \times m$  covariance matrix.

The GMM problem is *under-identified* if  $m < k$ , *just-identified* if  $m = k$ , and *over-identified* if  $m > k$ .

If  $m > k$ , there are *over-identifying* moments that can be used to improve estimation efficiency and/or test the internal consistency of the model.

Suppose an i.i.d. sample  $z_1, \dots, z_n$  from the data generation process. A *GMM estimator* of  $\theta_0$  is a vector  $T_n$  that minimizes the generalized distance of the sample moments from zero,

$$(2) \quad Q_n(\theta) = \frac{1}{2} \mathbf{g}_n(\theta)' \mathbf{W}_n(\tau_n) \mathbf{g}_n(\theta), \quad \text{with}$$

$$\mathbf{g}_n(\theta) \equiv \frac{1}{n} \sum_{t=1}^n g(z_t, \theta),$$

$\mathbf{W}_n(\theta)$  is a  $m \times m$  positive definite symmetric matrix, in general depending on  $\theta$ , evaluated at some sequence of “preliminary estimates”  $\tau_n$ .

The  $W_n(\tau_n)$  define a "distance metric". Let  $W_n = W_n(\tau_n)$ . Assume that  $W_n(\theta)$  converges in probability uniformly in  $\theta$  to  $W(\theta)$ , a continuous positive definite limit. Let  $W = \text{plim } W_n$ . If  $\text{plim } \tau_n = \theta_0$ , then  $\text{plim } W_n(\tau_n) = W(\theta_0) = W$ .

It is unnecessary to know the form of the log likelihood function  $l(z, \theta)$  in order to calculate the GMM estimator, and in fact GMM estimation is particularly useful when  $l(z, \theta)$  is not completely specified and only the moment condition  $E g(z, \theta_0) = 0$  can be assumed. However, some statistical properties of GMM estimators (e.g., possibly asymptotic efficiency) will depend on the interplay of  $g(z, \theta)$  and  $l(z, \theta)$ .

$\Omega(\theta) \equiv E g(z, \theta)g(z, \theta)'$   $m \times m$  covariance matrix of the moments.

Efficient weighting requires  $\text{plim } W_n = \Omega(\theta_0)^{-1}$ . Call a GMM estimator that has  $\text{plim } W_n = \Omega(\theta_0)^{-1}$  a *best* GMM estimator. A good candidate for  $W_n$  is  $\Omega_n(\tau_n)^{-1}$ , where

$$(3) \quad \Omega_n(\theta) = \frac{1}{n} \sum_{t=1}^n g(z_t, \theta)g(z_t, \theta)',$$

and  $\tau_n$  is a consistent preliminary estimate of  $\theta_0$ .

One good way to get a consistent preliminary estimator  $\tau_n$  is to first minimize a GMM criterion using the identity matrix  $I_m$  for  $W_n$ .

$G(\theta) \equiv -E \nabla_{\theta} g(z, \theta)$   $m \times k$  Jacobean matrix

$$(4) \quad G_n(\theta) = \frac{-1}{n} \sum_{t=1}^n \nabla_{\theta} g(z_t, \theta).$$

$G_n(\tau_n)$  evaluated at a consistent preliminary estimate  $\tau_n$  of  $\theta_0$  has probability limit  $G(\theta_0)$ . Hereafter,  $\Omega_n$  and  $G_n$  will be used as shorthand for  $\Omega_n(\tau_n)$  and  $G_n(\tau_n)$ , respectively, and  $\Omega$  and  $G$  will be used as shorthand for  $\Omega(\theta_0)$  and  $G(\theta_0)$ .

A GMM estimator with a distance metric  $W_n$  that converges in probability to a positive definite matrix  $W$  will be CAN with an asymptotic covariance matrix  $(G'WG)^{-1}G'W\Omega WG(G'WG)^{-1}$ , and a best GMM estimator with a distance metric  $W_n$  that converges in probability to  $\Omega(\theta_0)^{-1}$  will be CAN with an asymptotic covariance matrix  $(G'\Omega^{-1}G)^{-1}$ . The following lemma justifies the sorbeque “best”:

**Lemma 3.1.**

$$(G'WG)^{-1}G'W\Omega WG(G'WG)^{-1} - (G'\Omega^{-1}G)^{-1}$$

*is positive semidefinite.*

## Special cases

- $f(z, \theta)$  is a scalar function with the property that  $E f(z, \theta_0) \leq E f(z, \theta)$ . Minimize the sample analog

$$f_n(\theta) = \frac{1}{n} \sum_{t=1}^n f(z_t, \theta) ; \text{ this is called an } \textit{extremum}$$

*estimator*. A leading example is  $f(z, \theta) = -l(z, \theta)$ , the negative of a full or limited information log likelihood function. A GMM estimator with moments  $g(z, \theta) = \nabla_{\theta} f(z, \theta)$  and any distance metric has the property that the GMM criterion is minimized at the extremum estimator. When one can guarantee that the GMM criterion has no roots other than the extremum estimator, then one can treat the extremum estimator in its equivalent GMM form.

- $z = (y, x, w)$  and  $g(z, \theta) = w'(y - x\theta)$ , so that the moment conditions assert orthogonality in the population between *instruments*  $w$  and regression *disturbances*  $\varepsilon = y - x\theta_0$ . For this problem, GMM specializes to two-stage least squares (2SLS), or if  $w = x$ , to OLS.
- These linear regression setups generalize directly to nonlinear regression orthogonality conditions based on the form  $g(z, \theta) = w'(y - h(x, \theta))$ , where  $h$  is a function that is known up to the parameter  $\theta$  and by assumption a vector of  $m$  exogenous variables  $w$  are orthogonal to the regression disturbances  $y - h(x, \theta_0)$ .

Denote *convergence in probability* by  $\rightarrow_p$ , and *convergence in distribution* by  $\rightarrow_d$ .

If a sequence of events occur with probability approaching one, we say that they occur *in probability limit*.

A sequence of random variables  $Y_n$  is *stochastically bounded* if for each  $\varepsilon > 0$  there exists a constant  $M$  such that for all  $n$ ,  $\text{Prob}(|Y_n| > M) < \varepsilon$ .

We will sometimes use the notation  $Y_n = Y_0 + o_p$  for  $Y_n \rightarrow_p Y_0$  and  $Y_n = O_p(1)$  for a stochastically bounded sequence.

We will need some definitions for random functions on a subset  $\Theta$  of a Euclidean space  $\mathbb{R}^k$ . Let  $(S, F, P)$  denote a probability space. Define a *random function* as a mapping  $Y$  from  $\Theta \times S$  into  $\mathbb{R}$  with the property that for each  $\theta \in \Theta$ ,  $Y(\theta, \cdot)$  is measurable with respect to  $(S, F, P)$ . Note that  $Y(\theta, \cdot)$  is simply a random variable, and that  $Y(\cdot, s)$  is simply a function of  $\theta \in \Theta$ . Usually, the dependence of  $Y$  on the state of nature is suppressed, and we simply write  $Y(\theta)$ . A random function is also called a *stochastic process*, and  $Y(\cdot, s)$  is termed a *realization* of this process.



A random function  $Y(\theta, \cdot)$  is *almost surely continuous* at  $\theta_0 \in \Theta$  if for  $s$  in a set that occurs with probability one,  $Y(\cdot, s)$  is continuous in  $\theta$  at  $\theta_0$ . In detail, for each  $\varepsilon > 0$ , define

$$A_k(\varepsilon, \theta_0) = \left\{ s \in S \mid \sup_{|\theta - \theta_0| \leq 1/k} |Y(\theta, s) - Y(\theta_0, s)| > \varepsilon \right\}.$$

Almost sure continuity states that these sets converge monotonically as  $k \rightarrow \infty$  to a set  $A_0(\varepsilon, \theta_0)$  that has probability zero.

Example: the function  $Y(\theta, s) = \theta^s$  for  $\theta \in [0, 1]$  and  $s$  uniform on  $[0, 1]$  is continuous at  $\theta = 0$  for

every  $s$ , but  $A_k(\varepsilon, 0) = [0, \frac{-\log \varepsilon}{\log k})$  has positive

probability for all  $k$ .

Example: The exceptional sets  $A_k(\varepsilon, \theta)$  can vary with  $\theta$ , and there is no requirement that there be a set of  $s$  with probability one, or for that matter with positive probability, where  $Y(\theta, s)$  is continuous for all  $\theta$ . If  $\theta \in [0, 1]$  and  $s$  is uniform on  $[0, 1]$ ,  $Y(\theta, s) = 1$  if  $\theta \geq s$  and  $Y(\theta, s) = 0$  otherwise is almost surely continuous everywhere but has a discontinuity.

**Lemma 3.2.** *For sequences of random vectors  $Y_n$  and  $Z_n$ , (1) for  $c$  a constant,  $Y_n \rightarrow_p c$  if and only if  $Y_n \rightarrow_d c$ ; (2) if  $Y_n \rightarrow_d Y_0$  and  $Z_n - Y_n \rightarrow_p 0$ , then  $Z_n \rightarrow_d Y_0$ ; and (3) if  $Y_n \rightarrow_d Y_0$  and  $f$  is a continuous function on an open set containing the support of  $Y_0$ , then  $f(Y_n) \rightarrow_d f(Y_0)$ .*

**Lemma 3.3 (Uniform WLLN).** *Assume  $Y_i(\theta)$  are independent identically distributed random functions with a finite mean  $\psi(\theta)$  for  $\theta$  in a closed bounded set  $\Theta \subseteq \mathbb{R}^k$ . Assume  $Y_i(\cdot)$  is almost surely continuous at each  $\theta \in \Theta$ . Assume that  $Y_i(\cdot)$  is dominated; i.e., there exists a random variable  $Z$  with a finite mean that satisfies  $Z \geq \sup_{\theta \in \Theta} |Y_1(\theta)|$ . Then  $\psi(\theta)$  is*

*continuous in  $\theta$  and  $X_n(\theta) = \frac{1}{n} \sum_{i=1}^n$  satisfies*

$$\sup_{\theta \in \Theta} |X_n(\theta) - \psi(\theta)| \rightarrow_p 0.$$

**Lemma 3.4 (Continuous Mapping).** *If  $Y_n(\theta) \rightarrow_p Y_0(\theta)$  uniformly for  $\theta$  in  $\Theta \subseteq \mathbb{R}^k$ , random vectors  $\tau_0, \tau_n \in \Theta$  satisfy  $\tau_n \rightarrow_p \tau_0$ , and  $Y_0(\theta)$  is almost surely continuous at  $\tau_0$ , then  $Y_n(\tau_n) \rightarrow_p Y_0(\tau_0)$ .*

**Theorem 3.1.** (Newey and McFadden (1994, Thm. 2.6 and Thm. 3.4)) *Consider an i.i.d. sample  $z_t$ , for  $t = 1, \dots, n$ ; the GMM criterion  $Q_n(\theta) = \frac{1}{2}g_n(\theta)'W_n g_n(\theta)$  given by (2), with  $W_n = W_n(\tau_n)$  and  $\tau_n$  a sequence of “preliminary estimates” converging in probability to a limit  $\tau_0$ ; the arrays  $\Omega_n(\theta)$  given by (3) and  $G_n(\theta)$  given by (4); and the GMM estimator  $T_n = \operatorname{argmin}_{\theta \in \Theta} Q_n(\theta)$ . Assume (i) to (vii):*

- (i) *The domain  $\Theta$  of  $\theta$  is a compact subset of  $\mathbb{R}^k$  and  $\theta_0$  is in its interior.*
- (ii) *The log likelihood function  $l(z, \theta)$  is measurable in  $z$  for each  $\theta$ , and almost surely (with respect to  $z$ ) twice continuously differentiable with respect to  $\theta$  in a neighborhood of  $\theta_0$ .*

- (iii) *The function  $g$  is measurable in  $z$  for each  $\theta$ , and almost surely (with respect to  $z$ ) is continuous on  $\Theta$  and on a neighborhood of  $\theta_0$ , continuously differentiable in  $\theta$ , with the derivative Lipschitz; i.e., there is a function  $\alpha(z)$  with finite expectation such that for  $\theta, \theta'$  in the neighborhood of  $\theta_0$ ,  $|\nabla_{\theta}g(z, \theta) - \nabla_{\theta}g(z, \theta')| \leq \alpha(z)|\theta - \theta'|$ .*
- (iv)  *$Eg(z, \theta) = 0$  if and only if  $\theta = \theta_0$ .*
- (v)  *$\Omega(\theta_0)$  is a positive definite  $m \times m$  matrix and  $G(\theta_0)$  is an  $m \times k$  matrix of rank  $k$ .*
- (vi)  *$W(\theta)$  is a positive definite  $m \times m$  matrix that is continuous in  $\theta$ ,  $W_n(\theta) \rightarrow_p W(\theta)$  uniformly in  $\theta$ , and  $W_n \rightarrow_p W$ .*
- (vii) *There exists a function  $\alpha(z)$ , with finite expectation, that dominates  $g(z, \theta)g(z, \theta)'$  and  $\nabla_{\theta}g(z, \theta)$ ; i.e.,  $+\infty > E\alpha(z)$ ,  $|g(z, \theta)g(z, \theta)'| \leq \alpha(z)$ , and  $|\nabla_{\theta}g(z, \theta)| \leq \alpha(z)$ .*

*If an estimator  $T_n^*$  satisfies  $Q_n(T_n^*) \rightarrow_p \mathbf{0}$ , then  $T_n^* \rightarrow_p \mathbf{0}$ , and if  $n \cdot Q_n(T_n^*)$  is stochastically bounded, then  $n^{1/2} \cdot g_n(T_n^*)$  and  $n^{1/2} \cdot (T_n^* - \theta_0)$  are stochastically bounded. The unconstrained GMM estimator  $T_n$  satisfies these conditions and is consistent and asymptotically normal (CAN), with*

$$(5) \quad n^{1/2}(T_n - \theta_0) \rightarrow_d N(\mathbf{0}, (G'WG)^{-1}G'W\Omega WG(G'WG)^{-1}).$$

*If in addition either  $W_n \rightarrow_p \Omega^{-1}$ , or else just-identification (i.e.,  $m = k$ ) with  $W_n$  an arbitrary non-singular matrix, then  $T_n$  is a best GMM estimator that is CAN with  $B \equiv G'\Omega^{-1}G$  and*

$$(6) \quad n^{1/2}(T_n - \theta_0) \rightarrow_d N(\mathbf{0}, B^{-1}).$$

**Proof of Theorem 1.** Step 0 shows that  $n^{1/2} g_n(\theta_0)$  is asymptotically normal, that  $G_n(\theta)$ ,  $\Omega_n(\theta)$ , and  $W_n(\theta)$  converge in probability uniformly in  $\theta$  to  $G(\theta)$ ,  $\Omega(\theta)$ , and  $W(\theta)$ , respectively, and that  $n \cdot Q_n(\theta_0)$  is stochastically bounded. Step 1 shows for  $T_n^*$  satisfying  $Q_n(T_n^*) \rightarrow_p 0$  that  $T_n^* \rightarrow_p \theta_0$ . Step 2 shows for  $T_n^*$  satisfying  $n \cdot Q_n(T_n^*)$  stochastically bounded that  $n^{1/2} \cdot (T_n^* - \theta_0)$  is stochastically bounded. These two steps imply that a preliminary estimator  $\tau_n$  that uses an easily calculated distance metric such as  $I_m$  is consistent, and hence that  $\Omega_n(\tau_n) \rightarrow_p \Omega$  and  $G_n(\tau_n) \rightarrow_p G$ . They also imply that  $T_n$  is consistent and stochastically bounded. Step 3 applies the mean value theorem to the first-order condition for  $T_n$  and uses rules for asymptotic limits to show that  $n^{1/2}(T_n - \theta_0)$  is asymptotically normal.

**Step 0:** The expression  $\mathbf{g}_n(\boldsymbol{\theta}_o)$  is a sample average of i.i.d. random vectors with mean zero and finite covariance matrix  $\boldsymbol{\Omega}$ . Then the Lindeberg-Levy central limit theorem implies

$$(7) \quad \boldsymbol{\Omega}^{-1/2} \mathbf{n}^{1/2} \mathbf{g}_n(\boldsymbol{\theta}_o) \equiv \mathbf{U}_n \rightarrow_d \mathbf{U} \sim \mathbf{N}(\mathbf{0}, \mathbf{I}_m).$$

The expressions  $\mathbf{g}_n(\boldsymbol{\theta})$ ,  $\mathbf{G}_n(\boldsymbol{\theta})$ , and  $\boldsymbol{\Omega}_n(\boldsymbol{\theta})$  are sample averages that converge in probability for each fixed  $\boldsymbol{\theta}$  to  $\mathbf{E}g(\boldsymbol{\theta})$ ,  $\mathbf{G}(\boldsymbol{\theta})$ , and  $\boldsymbol{\Omega}(\boldsymbol{\theta})$ , respectively, by Kinchine's law of large numbers. Conditions (i), (iii), and (vii) establish that these functions are dominated and almost surely continuous on the compact set  $\Theta$ . Then the hypotheses of Lemma 3 are satisfied, so the convergence is uniform in  $\boldsymbol{\theta}$ . Condition (vi) gives  $\mathbf{W}_n(\boldsymbol{\theta}) \rightarrow_p \mathbf{W}(\boldsymbol{\theta})$  uniformly in  $\boldsymbol{\theta}$ . This condition plus (7) implies by Lemma 2 that  $\mathbf{n} \cdot \mathbf{Q}_n(\boldsymbol{\theta}_o)$  is stochastically bounded.

**Step 1: Consider any estimator  $T_n^*$  that satisfies  $Q_n(T_n^*) \rightarrow_p 0$ . For each fixed  $\theta$ , the Kinchine law of large numbers implies that  $g_n(\theta) \rightarrow_p Eg(\theta)$ . We have established that the convergence in probability of  $g_n(\theta)$  to  $Eg(\theta)$  is uniform in  $\theta$ . Combined with the condition  $W_n \rightarrow_p W$  from (vi), this implies  $Q_n(\theta) \rightarrow_p \frac{1}{2}(Eg(\theta))'W(Eg(\theta))$  uniformly in  $\theta$ . Outside each small neighborhood of  $\theta_0$ , the probability limit of  $Q_n(\theta)$  is uniformly bounded away from zero by (iv). Therefore,  $T_n^*$  is, with probability approaching one, within each small neighborhood. This establishes consistency of  $T_n^*$ .**



**Step 2: Consider any estimator  $T_n^*$  that satisfies  $n \cdot Q_n(T_n^*)$  stochastically bounded. This condition implies  $Q_n(T_n^*) \rightarrow_p 0$ , and thus  $T_n^* \rightarrow_p \theta_0$  by Step 1. The mean value theorem and (7) give**

$$(8) \quad \begin{aligned} n^{1/2} \mathbf{g}_n(T_n^*) &= n^{1/2} \mathbf{g}_n(\theta_0) - \mathbf{G}_n n^{1/2}(T_n^* - \theta_0) \\ &= \mathbf{\Omega}^{1/2} \mathbf{U}_n - \mathbf{G}_n n^{1/2}(T_n^* - \theta_0), \end{aligned}$$

with  $\mathbf{G}_n$  evaluated at points between  $T_n^*$  and  $\theta_0$ . Apply the triangle inequality for the GMM distance metric to the vector  $\mathbf{G}_n n^{1/2}(T_n^* - \theta_0) = \mathbf{\Omega}^{1/2} \mathbf{U}_n - n^{1/2} \mathbf{g}_n(T_n^*)$  to obtain

$$(9) \quad \begin{aligned} \frac{1}{2} n^{1/2}(T_n^* - \theta_0)' \mathbf{G}_n' \mathbf{W}_n \mathbf{G}_n n^{1/2}(T_n^* - \theta_0) &\leq \\ \frac{1}{2} \mathbf{U}_n' \mathbf{\Omega}^{1/2} \mathbf{W}_n \mathbf{\Omega}^{1/2} \mathbf{U}_n + n \cdot Q_n(T_n^*). \end{aligned}$$

The first term on the right-hand-side of (9) converges in distribution by Lemma 2, and hence is stochastically bounded. Together with the hypothesis that  $n \cdot Q_n(T_n^*)$  is stochastically bounded, this implies that  $n^{1/2}(T_n^* - \theta_0)' \mathbf{G}_n' \mathbf{W}_n \mathbf{G}_n n^{1/2}(T_n^* - \theta_0)$  is stochastically bounded.

The uniform convergence of  $G_n(\theta)$  and Lemma 4 imply  $G_n' W_n G_n \rightarrow_p G' W G$  positive definite. Let  $\lambda > 0$  be the smallest characteristic root of  $G' W G$ . Then in probability limit

$$(10) \quad (\lambda/2) \cdot n^{1/2} \cdot |T_n^* - \theta_0|^2 \leq n^{1/2} (T_n^* - \theta_0)' G_n' W_n G_n n^{1/2} (T_n^* - \theta_0) = O_p(1),$$

establishing that  $n^{1/2}(T_n^* - \theta_0)$  is stochastically bounded. In (8), this implies that  $n^{1/2}g_n(T_n^*)$  is stochastically bounded.

**Step 3:** Consider the GMM estimator  $T_n = \operatorname{argmin}_{\theta \in \Theta} Q_n(\theta)$ . Then  $Q_n(T_n) \leq Q_n(\theta_0)$ , and the condition that  $n \cdot Q_n(\theta_0)$  is stochastically bounded implies by Steps 1 and 2 that  $T_n$  is consistent and  $n^{1/2}(T_n - \theta_0)$  is stochastically bounded. The first-order condition for  $T_n$  is  $0 = G(T_n)'W_n n^{1/2}g_n(T_n)$ . Substituting the mean value expansion (7) in this first-order condition gives

$$(11) \quad 0 = -G(T_n)'W_n \Omega^{1/2} U_n + G(T_n)'W_n G_n n^{1/2}(T_n - \theta_0).$$

We established in Step 2 that in probability limit,  $G(T_n)'W_n G_n$  is non-singular and  $(G(T_n)'W_n G_n)^{-1} \rightarrow_p (G'WG)^{-1}$ . Then,  $n^{1/2}(T_n - \theta_0) = (G(T_n)'W_n G_n)^{-1} G(T_n)'W_n \Omega^{1/2} U_n$  exists in probability limit. The array  $(G(T_n)'W_n G_n)^{-1}$  converges in probability, and hence in distribution, to  $(G'WG)^{-1}$ ; the array  $G(T_n)'W_n \Omega^{1/2}$  converges in probability, and hence in distribution, to  $G'W\Omega^{1/2}$ ; and  $U_n$  converges in distribution to  $U$ .

Then Lemma 2 implies that the continuous function that is the product of these terms converges in distribution to the product of the limits; i.e.,  $n^{1/2}(T_n - \theta_0) \rightarrow_d (G'WG)^{-1}G'W\Omega^{1/2}U$ , which is normal with covariance matrix  $(G'WG)^{-1}G'W\Omega WG(G'WG)^{-1}$ . This establishes (5). When  $W = \Omega^{-1}$  or  $m = k$ , (6) follows.  $\square$

The asymptotic covariance matrices  $(G'WG)^{-1}G'W\Omega WG(G'WG)^{-1}$  or  $B^{-1} = (G'\Omega^{-1}G)^{-1}$  can be estimated using  $G_n(\tau_n)$  and  $\Omega_n(\tau_n)$ , where  $\tau_n$  is any consistent (preliminary) estimator of  $\theta_0$ , by Lemmas 3 and 4. A practical procedure for estimation is to first estimate  $\theta_0$  using the GMM criterion with an arbitrary  $W_n$ , such as the  $m \times m$  identity matrix  $I_m$ . This produces an initial CAN estimator  $\tau_n$ . Then use the formulas above to estimate the asymptotically efficient  $W_n = \Omega_n(\tau_n)^{-1}$ , and use the GMM criterion with this distance metric to obtain the final estimator  $T_n$ .

Differentiating the identity  $\mathbf{0} \equiv \int g(\mathbf{z}, \boldsymbol{\theta}) e^{l(\mathbf{z}, \boldsymbol{\theta})} d\mathbf{z}$  with respect to  $\boldsymbol{\theta}$ , and evaluating the result at  $\boldsymbol{\theta}_0$

$$(15) \quad \Gamma \equiv \mathbf{E} g(\mathbf{z}, \boldsymbol{\theta}_0) \nabla_{\boldsymbol{\theta}} l(\mathbf{z}, \boldsymbol{\theta}_0)' \equiv -\mathbf{E} \nabla_{\boldsymbol{\theta}} g(\mathbf{z}, \boldsymbol{\theta}_0) \equiv \mathbf{G}.$$

It will sometimes be convenient to estimate  $\mathbf{G}$  by

$$(16) \quad \Gamma_n = \frac{1}{n} \sum_{t=1}^n g(\mathbf{z}_t, \boldsymbol{\tau}_n) \nabla_{\boldsymbol{\theta}} l(\mathbf{z}_t, \boldsymbol{\tau}_n)'.$$

In the maximum likelihood case  $g = \nabla_{\boldsymbol{\theta}} l$ , one has  $\boldsymbol{\Omega} = \Gamma = \mathbf{E} [\nabla_{\boldsymbol{\theta}} l(\mathbf{z}_t, \boldsymbol{\theta}_0)]' [\nabla_{\boldsymbol{\theta}} l(\mathbf{z}_t, \boldsymbol{\theta}_0)]'$  and by the information equality,  $\mathbf{G} = -\mathbf{E} \nabla_{\boldsymbol{\theta}\boldsymbol{\theta}} l(\mathbf{z}_t, \boldsymbol{\theta}_0) = \mathbf{E} [\nabla_{\boldsymbol{\theta}} l(\mathbf{z}_t, \boldsymbol{\theta}_0)]' [\nabla_{\boldsymbol{\theta}} l(\mathbf{z}_t, \boldsymbol{\theta}_0)]' = \boldsymbol{\Omega}$ , so that the asymptotic covariance matrix of the unconstrained estimator simplifies to  $\boldsymbol{\Omega}^{-1}$ .

$$\Gamma_n' \Omega_n^{-1} = \left[ \sum_{t=1}^n \nabla_{\theta} l(z_t, \tau_n) g(z_t, \tau_n)' \right] \left[ \sum_{t=1}^n g(z_t, \tau_n) g(z_t, \tau_n)' \right]^{-1} .$$

Each row of this array can be interpreted as the coefficients obtained from an OLS regression of the corresponding component of  $\nabla_{\theta} l(z_t, \tau_n)$  on  $g(z_t, \tau_n)$ . Then the right-hand side of the first-order condition for a best GMM estimator,  $0 = \Gamma_n' \Omega_n^{-1} \mathbf{g}_n(T_n)$ , can be usefully interpreted as the projection of  $\nabla_{\theta} l(z_t, \tau_n)$  onto the subspace spanned by  $g(z_t, \tau_n)$ . This is then the linear combination of  $g(z_t, \tau_n)$  that most closely approximates  $\nabla_{\theta} l(z_t, \tau_n)$ . The GMM estimator  $T_n$  sets this approximate score to zero. One implication of this result is that if  $g(z_t, \tau_n) = \nabla_{\theta} l(z_t, \tau_n)$ , then the projection returns this vector and  $\Gamma_n' \Omega_n^{-1}$  is the identity matrix. Another implication is that if  $g(z_t, \tau_n)$  contains  $\nabla_{\theta} l(z_t, \tau_n)$  plus other moments, then  $\Gamma_n' \Omega_n^{-1}$  will be the horizontal concatenation of an identity matrix and a matrix of zeros, so that the GMM first-order condition coincides with the condition for MLE, and the added moments are

given zero weight.

## THE NULL HYPOTHESIS AND THE CONSTRAINED GMM ESTIMATOR

Suppose there is an  $r$ -dimensional null hypothesis on the data generation process,

$$(17) \quad H_0: a(\theta_0) = 0,$$

where  $a(\cdot)$  is a  $r \times 1$  vector of continuously differentiable functions and the  $r \times k$  matrix  $A \equiv \nabla_{\theta} a(\theta_0)$  has rank  $r$ . The null hypothesis may be linear or nonlinear. A particularly simple case is  $H_0: \theta = \theta^0$ , or  $a(\theta) \equiv \theta - \theta^0$ , so the parameter vector  $\theta$  is completely specified under the null. Other examples are  $a(\theta_0) = \theta_{10}$ , a linear hypothesis that the first parameter is zero, and  $a(\theta_0) = (\theta_{10}/\theta_{20} - \theta_{30}/\theta_{40})$ , a non-linear hypothesis that two ratios of parameters are equal. In general there will be  $k-r$  parameters to be estimated when one imposes the null.

**We will consider alternatives to the null of the form**

$$(18) \quad \mathbf{H}_1: a(\theta_0) \neq \mathbf{0},$$

**or *asymptotically local* alternatives of the form**

$$(19) \quad \mathbf{H}_{1n}: a(\theta_0) = \delta n^{-1/2} \neq \mathbf{0}.$$

**For local alternatives we consider the sequence of problems where  $l(z, \theta)$  is the log likelihood of an observation,  $\theta_{no} = \theta_0 - A(A' A)^{-1} \delta n^{-1/2}$  is the sequence of true parameter values, and  $a_n(\theta) = \delta n^{-1/2} + A(\theta - \theta_0)$  is the sequence of (locally linear) constraints. These problems then satisfy  $a_n(\theta_{no}) = \mathbf{0}$  and  $a_n(\theta_0) = \delta n^{-1/2}$ . In econometric analysis, interesting alternatives are often sufficiently “local” in large samples so that asymptotic distributions under local alternatives give good estimates of power.**



One can define a *constrained* GMM estimator by optimizing the GMM criterion subject to the null hypothesis:

$$(20) \quad T_{an} = \operatorname{argmin}_{\theta \in \Theta} Q_n(\theta) \quad \text{subject to } a(\theta) = 0.$$

For local alternatives, the constraints become  $a_n(\theta) = \delta n^{-1/2} + A(\theta - \theta_0)$ . The following result establishes consistency of  $T_{an}$  under the null hypothesis or local alternatives:

**Lemma 3.5.** *Assume conditions (i)-(vii) in Theorem 1. Assume that under the null hypothesis the true parameter vector  $\theta_0$  satisfies the constraints  $a(\theta_0) = 0$ , and that in the sequence of local alternative problems the true parameter vectors  $\theta_{n0} = \theta_0 - A(A' A)^{-1} \delta n^{-1/2}$  satisfy the sequence of constraints  $a_n(\theta) = \delta n^{-1/2} + A(\theta - \theta_0) = 0$ . Then  $T_{an} \rightarrow_p \theta_0$  and  $n^{1/2} \cdot (T_{an} - \theta_0)$  is stochastically bounded.*

**Consider asymptotic normality of the constrained estimator under the null or local alternatives. Define a Lagrangian for  $T_{an}$ :  $L_n(\theta, \gamma) = Q_n(\theta) - a(\theta)' \gamma$ . In this expression,  $\gamma$  is the  $r \times 1$  vector of undetermined Lagrangian multipliers; these will be non-zero when the constraints are binding. The first-order conditions for solution of the constrained optimization problem are**

$$(21) \quad \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} n^{1/2} \nabla_{\theta} Q_n(T_{an}) - \nabla_{\theta} a(T_{an})' n^{1/2} \gamma_{an} \\ -n^{1/2} a(T_{an}) \end{bmatrix}.$$

**The Lagrangian multipliers  $\gamma_{an}$  are random variables. Lemma 5, and when applicable the argument given in the proof of Corollary 1, imply  $\nabla_{\theta} Q_n(T_{an}) \rightarrow_p -G' W E g(z, \theta_o) = 0$ . Further,  $\nabla_{\theta} a(T_{an}) \rightarrow_p A$ , implying  $A' \gamma_{an} = -\nabla_{\theta} Q_n(T_{an}) + o_p \rightarrow_p 0$ , and since  $A$  is of full rank,  $\gamma_{an} \rightarrow_p 0$ .**

The argument for asymptotic normality parallels the argument given in Theorem 1 for the unconstrained estimator, and relates the asymptotic distributions of  $T_n$ ,  $T_{an}$ , and  $\gamma_{an}$ . Noting that  $T_{an}$  satisfies (8), and then approximating  $G_n$  by  $G$  and  $W_n$  by  $W$ , one gets

$$\begin{aligned} n^{1/2} \mathbf{g}_n(T_{an}) &= n^{1/2} \mathbf{g}_n(\theta_o) - G_n n^{1/2} (T_{an} - \theta_o) \\ &= \Omega^{1/2} U_n - G n^{1/2} (T_{an} - \theta_o) + o_p \end{aligned}$$

and  $n^{1/2} \nabla_{\theta} Q_n(T_{an}) = G' W n^{1/2} \mathbf{g}_n(T_{an}) + o_p$ . Under local alternatives (or the null when  $\delta = 0$ ),

$$\begin{aligned} n^{1/2} a(T_{an}) &= n^{1/2} a(\theta_o) + A n^{1/2} (T_{an} - \theta_o) + o_p \\ &\equiv \delta + A n^{1/2} (T_{an} - \theta_o) + o_p. \end{aligned}$$

Substituting these in the first-order conditions and letting  $C = G' W G$  yields

$$(22) \quad \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} G' W \Omega^{1/2} U_n \\ -\delta \end{bmatrix} - \begin{bmatrix} C & A' \\ A & 0 \end{bmatrix} \begin{bmatrix} n^{1/2} (T_{an} - \theta_o) \\ n^{1/2} \gamma_{an} \end{bmatrix} + o_p.$$

**From the formulas for partitioned inverses,**

$$\begin{bmatrix} C & A' \\ A & 0 \end{bmatrix}^{-1} = \begin{bmatrix} C^{-1} - C^{-1}A'(AC^{-1}A')^{-1}AC^{-1} & C^{-1}A'(AC^{-1}A')^{-1} \\ (AC^{-1}A')^{-1}AC^{-1} & -(AC^{-1}A')^{-1} \end{bmatrix},$$

**Applying this to (22) yields (23):**

$$\begin{bmatrix} n^{1/2}(T_{an} - \theta_o) \\ n^{1/2}\gamma_{an} \end{bmatrix} = \begin{bmatrix} -C^{-1}A'(AC^{-1}A')^{-1} \\ (AC^{-1}A')^{-1} \end{bmatrix} \delta + \begin{bmatrix} C^{-1} - C^{-1}A'(AC^{-1}A')^{-1}AC^{-1} \\ (AC^{-1}A')^{-1}AC^{-1} \end{bmatrix} G'W\Omega^{1/2}U_n + o_p.$$

**From Corollary 1,  $n^{1/2}(T_n - \theta_o) = C^{-1}G'W\Omega^{1/2}U_n + o_p$ .  
Substitute this in (23) to conclude that**

$$(24) \quad \begin{aligned} n^{1/2}(T_n - T_{an}) &= C^{-1}A'(AC^{-1}A')^{-1}AC^{-1}G'W\Omega^{1/2}U_n \\ &\quad + C^{-1}A'(AC^{-1}A')^{-1}\delta + o_p. \end{aligned}$$

**Note that  $An^{1/2}(T_n - T_{an}) = AC^{-1}G'W\Omega^{1/2}U_n + \delta + o_p$ ,  
and that  $n^{1/2}(T_n - T_{an})$  can be represented as the  
linear transformation  $C^{-1}A'(AC^{-1}A')^{-1}$  of  
 $An^{1/2}(T_n - T_{an})$ . We also have**

$$(25) \quad \begin{aligned} n^{1/2}a(T_n) &= n^{1/2}a(\theta_o) + A n^{1/2}(T_n - \theta_o) + o_p \\ &= AC^{-1}G'W\Omega^{1/2}U_n + \delta + o_p. \end{aligned}$$

**The expansion**

$$\mathbf{n}^{1/2} \mathbf{g}_n(T_{\text{an}}) = \mathbf{G}' \mathbf{W} \mathbf{\Omega}^{1/2} \mathbf{U}_n - \mathbf{G}' \mathbf{W} \mathbf{G} \mathbf{n}^{1/2} (T_{\text{an}} - \boldsymbol{\theta}_0) + o_p$$

**combined with (23) and**

$$\mathbf{K} = (\mathbf{I}_m - \mathbf{G} \mathbf{C}^{-1} \mathbf{G}' \mathbf{W} + \mathbf{G} \mathbf{C}^{-1} \mathbf{A}' (\mathbf{A} \mathbf{C}^{-1} \mathbf{A}')^{-1} \mathbf{A} \mathbf{C}^{-1} \mathbf{G}' \mathbf{W})$$

**implies**

$$\begin{aligned} \mathbf{n}^{1/2} \mathbf{g}_n(T_{\text{an}}) &= \mathbf{K} \mathbf{\Omega}^{1/2} \mathbf{U}_n \\ &\quad + \mathbf{G} \mathbf{C}^{-1} \mathbf{A}' (\mathbf{A} \mathbf{C}^{-1} \mathbf{A}')^{-1} \boldsymbol{\delta} + o_p, \end{aligned}$$

**and**

$$\begin{aligned} \mathbf{n}^{1/2} \nabla_{\boldsymbol{\theta}} \mathbf{Q}_n(T_{\text{an}}) &= \mathbf{G}' \mathbf{W} \mathbf{n}^{1/2} \mathbf{g}_n(T_{\text{an}}) \\ &= \mathbf{A}' (\mathbf{A} \mathbf{C}^{-1} \mathbf{A}')^{-1} \mathbf{A} \mathbf{C}^{-1} \mathbf{G}' \mathbf{W} \mathbf{\Omega}^{1/2} \mathbf{U}_n \\ &\quad + \mathbf{A}' (\mathbf{A} \mathbf{C}^{-1} \mathbf{A}')^{-1} \boldsymbol{\delta} + o_p. \end{aligned}$$

**Then,**

$$\begin{aligned} (26) \quad \mathbf{A} \mathbf{C}^{-1} \mathbf{n}^{1/2} \nabla_{\boldsymbol{\theta}} \mathbf{Q}_n(T_{\text{an}}) &= \mathbf{A} \mathbf{C}^{-1} \mathbf{G}' \mathbf{W} \mathbf{n}^{1/2} \mathbf{g}_n(T_{\text{an}}) + o_p \\ &= \mathbf{A} \mathbf{C}^{-1} \mathbf{G}' \mathbf{W} \mathbf{\Omega}^{1/2} \mathbf{U}_n + \boldsymbol{\delta} + o_p. \end{aligned}$$

**Table 1 summarizes the results. The table shows that the  $r \times 1$  vectors  $An^{1/2}(T_n - T_{an})$ ,  $n^{1/2}a(T_n)$ ,  $(AC^{-1}A')n^{1/2}\gamma_{an}$ , and  $AC^{-1}n^{1/2}\nabla_{\theta}Q_n(T_{an})$  all equal  $AC^{-1}G'W\Omega^{1/2}U_n + \delta + o_p$ . Consequently, they are asymptotically equivalent and asymptotically normal with mean  $\delta$  and non-singular covariance matrix  $A(G'WG)^{-1}G'W\Omega WG(G'WG)^{-1}A'$ . This table shows that all the statistics can be expressed as linear transformations of  $n^{1/2}(T_n - \theta_0)$ . This makes it simple to determine the asymptotic distributions of tests that use these statistics.**

**The asymptotic covariance matrices for the Table 1 statistics follow from their formulas and the result that  $U_n$  is asymptotically standard normal, and are given in Table 2. For a best GMM estimator, with  $W = \Omega^{-1}$  implying that  $H \equiv G'W\Omega WG = G'\Omega^{-1}G = C = B$ , the asymptotic covariance matrices simplify considerably. The asymptotic covariances matrices always satisfy**

$$\begin{aligned} \mathbf{acov}(T_n - T_{an}) &= \mathbf{acov}(T_n) + \mathbf{acov}(T_{an}) - \mathbf{acov}(T_n, T_{an}) \\ &\quad - \mathbf{acov}(T_{an}, T_n), \end{aligned}$$

but for a best GMM estimator one has  $\text{acov}(T_n, T_{an}) = \text{acov}(T_{an})$ , giving the simplification

$$(27) \quad \text{acov}(T_n - T_{an}) = \text{acov}(T_n) - \text{acov}(T_{an})$$

*or the variance of the difference equals the difference of the variances.* This proposition is familiar in a maximum likelihood context where the variance in the deviation between an efficient estimator and any other estimator equals the difference of the variances. We see here that it also applies to *relatively* efficient GMM estimators that use available moments and constraints optimally.

**Table 1. The Statistics and their Relationships**

	Statistic	Formula (with $C = G'WG$ )	Transformations of Other Statistics
1	$n^{1/2}g_n(\theta_o)$	$\Omega^{1/2}U_n + o_p$	---
2	$n^{1/2}(T_n - \theta_o)$	$C^{-1}G'W\Omega^{1/2}U_n + o_p$	$C^{-1}G'Wn^{1/2}g_n(\theta_o)$
3	$n^{1/2}(T_{an} - \theta_o)$	$-C^{-1}A'(AC^{-1}A')^{-1}\delta + [C^{-1} - C^{-1}A'(AC^{-1}A')^{-1}AC^{-1}]G'W\Omega^{1/2}U_n + o_p$	$n^{1/2}(T_n - \theta_o) - C^{-1}A'(AC^{-1}A')^{-1}n^{1/2}a(T_n)$
4	$n^{1/2}(T_n - T_{an})$	$C^{-1}A'(AC^{-1}A')^{-1}\delta + C^{-1}A'(AC^{-1}A')^{-1}AC^{-1}G'W\Omega^{1/2}U_n + o_p$	$C^{-1}A'(AC^{-1}A')^{-1}n^{1/2}a(T_n)$
5	$A n^{1/2}(T_n - T_{an})$	$\delta + AC^{-1}G'W\Omega^{1/2}U_n + o_p$	$n^{1/2}a(T_n)$
6	$n^{1/2}\gamma_{an}$	$(AC^{-1}A')^{-1}\delta + (AC^{-1}A')^{-1}AC^{-1}G'W\Omega^{1/2}U_n + o_p$	$(AC^{-1}A')^{-1}n^{1/2}a(T_n)$
7	$AC^{-1}A'n^{1/2}\gamma_{an}$	$\delta + AC^{-1}G'W\Omega^{1/2}U_n + o_p$	$n^{1/2}a(T_n)$
8	$n^{1/2}a(T_n)$	$\delta + AC^{-1}G'W\Omega^{1/2}U_n + o_p$	$\delta + A n^{1/2}(T_n - \theta_o)$
9	$n^{1/2}\nabla_{\theta}Q_n(T_{an})$	$A'(AC^{-1}A')^{-1}\delta + A'(AC^{-1}A')^{-1}AC^{-1}G'W\Omega^{1/2}U_n + o_p$	$A'(AC^{-1}A')^{-1}n^{1/2}a(T_n)$
10	$AC^{-1}n^{1/2}\nabla_{\theta}Q_n(T_{an})$	$\delta + AC^{-1}G'W\Omega^{1/2}U_n + o_p$	$n^{1/2}a(T_n)$

**Table 2. Asymptotic Covariance Matrices**(Note:  $B = G'\Omega^{-1}G$ ,  $C = G'WG$ ,  $H = G'W\Omega WG$ )

	Statistic	Asymptotic Covariance Matrix	Asymptotic Covariance Matrix if $W = \Omega^{-1}$
1	$n^{1/2}g_n(\theta_o)$	$\Omega$	$\Omega$
2	$n^{1/2}(T_n - \theta_o)$	$C^{-1}HC^{-1}$	$B^{-1}$
3	$n^{1/2}(T_{an} - \theta_o)$	$[C^{-1} - C^{-1}A'(AC^{-1}A')^{-1}AC^{-1}]H[C^{-1} - C^{-1}A'(AC^{-1}A')^{-1}AC^{-1}]$	$B^{-1} - B^{-1}A'(AB^{-1}A')^{-1}AB^{-1}$
4	$n^{1/2}(T_n - T_{an})$	$C^{-1}A'(AC^{-1}A')^{-1}AC^{-1}HC^{-1}A'(AC^{-1}A')^{-1}AC^{-1}$	$B^{-1}A'(AB^{-1}A')^{-1}AB^{-1}$
5	$A n^{1/2}(T_n - T_{an})$	$AC^{-1}HC^{-1}A'$	$AB^{-1}A'$
6	$n^{1/2}\gamma_{an}$	$(AC^{-1}A')^{-1}AC^{-1}HC^{-1}A'(AC^{-1}A')^{-1}$	$(AB^{-1}A')^{-1}$
7	$AC^{-1}A'n^{1/2}\gamma_{an}$	$AC^{-1}HC^{-1}A'$	$AB^{-1}A'$
8	$n^{1/2}a(T_n)$	$AC^{-1}HC^{-1}A'$	$AB^{-1}A'$
9	$n^{1/2}\nabla_{\theta}Q_n(T_{an})$	$A'(AC^{-1}A')^{-1}AC^{-1}HC^{-1}A'(AC^{-1}A')^{-1}A$	$A'(AB^{-1}A')^{-1}A$
10	$AC^{-1}n^{1/2}\nabla_{\theta}Q_n(T_{an})$	$AC^{-1}HC^{-1}A'$	$AB^{-1}A'$



### 3. THE TEST STATISTICS

The test statistics for the null hypothesis fall into three major classes, sometimes called the *trinity*. *Wald statistics* are based on deviations of the unconstrained estimates from values consistent with the null. *Lagrange Multiplier (LM)* or *Score statistics* are based on deviations of the constrained estimates from values solving the unconstrained problem. *Distance metric statistics* for best GMM estimators are based on differences in the GMM criterion between the unconstrained and constrained estimators. In the case of maximum likelihood estimation, the distance metric statistic is asymptotically equivalent to the *likelihood ratio statistic*. There are several variants for Wald statistics in the case of the general non-linear hypothesis; these reduce to the same expression in the simple case where the parameter vector is completely determined under the null. The same is true for LM statistics.

**There are often significant computational advantages to using one member or variant of the trinity rather than another. On the other hand, the Wald and LM statistics are all *asymptotically equivalent*, and for best GMM estimators the distance metric statistic is also asymptotically equivalent. Thus, at least to first-order asymptotic approximation, there is no statistical reason to choose between them. This pattern of first-order asymptotic equivalence for GMM estimates is exactly the same as for maximum likelihood estimates.**

**Table 3 gives the test statistics that can be used for the hypothesis  $a(\theta_0) = 0$ . For best GMM estimators with  $W = \Omega^{-1}$ , the full trinity of tests are available. Some of the test statistics that are available for best GMM estimators do not have versions that are asymptotically equivalent for general GMM estimators, and the corresponding cells are omitted from the table.**

**The central result is that all of the test statistics in each column are asymptotically equivalent under the null hypothesis or a local alternative to the null. Under the null, they have a common limiting chi-square distribution with degrees of freedom  $r$  equal to the dimension of the null hypothesis. Under a local alternative, they have a common limiting non-central chi-square distribution with  $r$  degrees of freedom and non-centrality parameter  $\delta' [AC^{-1}HC^{-1}A']^{-1} \delta$  in the general case and  $\delta' (AB^{-1}A')^{-1} \delta$  in the best estimator case.**

It is useful to relate the expression for the non-centrality parameter to outputs from econometric estimation packages. Typically, a package that does GMM estimation, or one of its specializations such as maximum likelihood or non-linear least squares, will automatically estimate  $\Omega_n^{-1}$  and use it as the distance metric, and will supply an estimate  $V$  of the covariance matrix of the estimates; namely  $V = (G_n' \Omega_n^{-1} G_n)^{-1}/n$ , where  $G_n$  and  $\Omega_n$  are estimates of  $G$  and  $\Omega$  respectively. If the alternative to the null is  $H_1: a(\theta_0) = c$ , then  $\delta = cn^{1/2}$ , and the non-centrality parameter written in terms of  $V$  and  $c$  is  $\delta'(AB^{-1}A')^{-1}\delta = c'(AVA')^{-1}c$ .

**Table 3. Test Statistics for GMM Estimators**(Note:  $B = G' \Omega^{-1} G$ ,  $C = G' W G$ ,  $H = G' W \Omega W G$ )

	General Estimators with $W \neq \Omega^{-1}$	Best Estimators with $W = \Omega^{-1}$
<i>Wald Statistics</i>		
$W_{1n}$	$na(T_n)'[AC^{-1}HC^{-1}A']^{-1}a(T_n)$	$na(T_n)'[AB^{-1}A']^{-1}a(T_n)$
$W_{2n}$ , flavor 1	$n(T_n - T_{an})' \text{acov}(T_n - T_{An})^{-1}(T_n - T_{an})$	$n(T_n - T_{an})' \{ \text{acov}(T_n) - \text{acov}(T_{An}) \}^{-1}(T_n - T_{an})$
$W_{2n}$ , flavor 2	$n(T_n - T_{an})' A' [AC^{-1}HC^{-1}A']^{-1} A(T_n - T_{an})$	$n(T_n - T_{an})' A' (AB^{-1}A')^{-1} A(T_n - T_{an})$
$W_{3n}$	---	$n(T_n - T_{an})' B(T_n - T_{an})$
<i>Lagrange Multiplier Statistics</i>		
$LM_{1n}$	$n\gamma_{an}' AC^{-1}A' [AC^{-1}HC^{-1}A']^{-1} AC^{-1}A' \gamma_{an}$	$n\gamma_{an}' AB^{-1}A' \gamma_{an}$
$LM_{2n}$ , flavor 1	$n\nabla_{\theta} Q_n(T_{an})' [A'(AC^{-1}A')^{-1} AC^{-1}HC^{-1}A' (AC^{-1}A')^{-1} A]^{-1} \nabla_{\theta} Q_n(T_{an})$	$n\nabla_{\theta} Q_n(T_{an})' \{ A'(AB^{-1}A')^{-1} A \}^{-1} \nabla_{\theta} Q_n(T_{an})$
$LM_{2n}$ , flavor 2	$n\nabla_{\theta} Q_n(T_{an})' A' [AC^{-1}HC^{-1}A']^{-1} A \nabla_{\theta} Q_n(T_{an})$	$n\nabla_{\theta} Q_n(T_{an})' B^{-1} A' (AB^{-1}A')^{-1} AB^{-1} \nabla_{\theta} Q_n(T_{an})$
$LM_{3n}$	---	$n\nabla_{\theta} Q_n(T_{an})' B^{-1} \nabla_{\theta} Q_n(T_{an})$
<i>Distance Metric Statistic</i>		
$DM_n$	---	$2n[Q_n(T_{an}) - Q_n(T_n)]$
<i>Asymptotic Distribution Under the Null:</i>	$\chi^2(r)$	$\chi^2(r)$
<i>Asymptotic Distribution Under Local Alternatives</i>	$\chi^2(r, nc)$	$\chi^2(r, nc)$
Non-centrality Parameter (nc)	$\delta'(AC^{-1}HC^{-1}A')^{-1}\delta$	$\delta'(AB^{-1}A')^{-1}\delta$

FIGURE 1. GMM TESTS

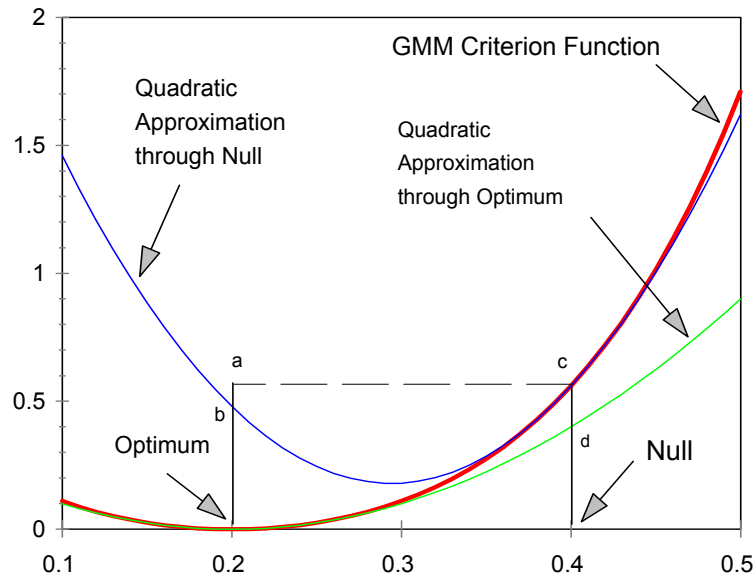


Figure 1 illustrates the relationship between distance metric (DM), Wald (W), and Score (LM) tests for a best GMM estimator. In the case of maximum likelihood estimation, this figure is inverted, the criterion is log likelihood rather than the distance metric, and the DM test is replaced by the likelihood ratio test. The “Optimum” and “Null” points on the  $\theta$  axis give the unconstrained ( $T_n$ ) and constrained ( $T_{an}$ ) estimators, respectively. The GMM criterion function is plotted, along with quadratic approximations to this function through the respective arguments  $T_n$  and  $T_{an}$ .

**The Wald statistic (W) can be interpreted as twice the difference in the height at  $T_n$  and  $T_{an}$  of the quadratic approximation through the optimum; the height d in the figure. The Lagrange Multiplier (LM) statistic can be interpreted as twice the difference in the height at  $T_n$  and  $T_{an}$  of the quadratic approximation through the null; the difference a - b in the figure. The Distance Metric (DM) statistic is twice the difference in the height at  $T_n$  and  $T_{an}$  of the GMM criterion, the height c in the figure. Note that if the criterion function were exactly quadratic, then the three statistics would be identical.**

The Wald statistic  $W_{1n}$  asks how close are the unconstrained estimators to satisfying the constraints; i.e., how close to zero is  $a(T_n)$ ? This variety of the test is particularly useful when the unconstrained estimator is available and the matrix  $A$  is easy to compute. For example, when the null is that a subvector of parameters equal constants, then  $A$  is a selection matrix that picks out the corresponding rows and columns of  $\text{acov}(T_n) = C^{-1}HC^{-1}$  (which reduces to  $B^{-1}$  for a best estimator), and this test reduces to a quadratic form with the deviations of the estimators from their hypothesized values in the wings, and the inverse of their asymptotic covariance matrix in the center. In the special case  $H_0: \theta = \theta^0$ , one has  $A = I_k$ .



**The Wald test  $W_{2n}$  is useful if both the unconstrained and constrained estimators are available. For best GMM estimation, its first version requires only the readily available asymptotic covariance matrices of the two estimators, but for  $r < k$  requires calculation of a generalized inverse. Algorithms for this are available, but are often not as numerically stable as classical inversion algorithms because near zero and exact zero characteristic roots are treated very differently. The second version of  $W_{2n}$ , available for either general or best GMM estimators, involves only ordinary inverses, and is potentially quite useful for computation in applications.**

The Wald statistic  $W_{3n}$ , which is only available for best GMM estimators, treats the constrained estimators *as if they were constants with a zero asymptotic covariance matrix*. This statistic is particularly simple to compute when the unconstrained and constrained estimators are available, as no matrix differences or generalized inverses are involved, and the matrix  $A$  need not be computed. The statistic  $W_{2n}$  is at least as large as  $W_{3n}$  in finite samples, since the center of the second quadratic form is  $\text{acov}(T_n)^{-1}$  and the center of the first quadratic form is  $\{\text{acov}(T_n) - \text{acov}(T_{an})\}^-$ , while the tails are the same. Nevertheless, the two statistics are asymptotically equivalent.

The approach of Lagrange multiplier or score tests is to calculate the constrained estimator  $T_{an}$ , and then to base a statistic on the discrepancy from zero at this argument of a condition that would be zero if the constraint were not binding. The statistic  $LM_{1n}$  asks how close the Lagrangian multipliers  $\gamma_{an}$ , measuring the degree to which the hypothesized constraints are binding, are to zero. This statistic is easy to compute if the constrained estimation problem is actually solved by Lagrangian methods, and the multipliers are obtained as part of the calculation. The statistic  $LM_{2n}$  asks how close to zero is the gradient of the distance criterion, evaluated at the constrained estimator. This statistic is useful when the constrained estimator is available and it is easy to compute the gradient of the distance criterion, say using the algorithm to seek minimum distance estimates. The second version of  $LM_{2n}$  avoids computation of a generalized inverse.

The statistic  $LM_{3n}$  for best GMM estimators, bears the same relationship to  $LM_{2n}$  that  $W_{3n}$  bears to  $W_{2n}$ .

This flavor of the test statistic is particularly convenient to calculate when the gradient of the likelihood function is available, as it can be obtained by two auxiliary regressions starting from the constrained estimator  $T_{an}$ :

a. Regress  $\nabla_{\theta}l(z_t, T_{an})'$  on  $g(z_t, T_{an})$ , and retrieve fitted values  $\nabla_{\theta}l^*(z_t, T_{an})'$ .

b. Regress 1 on  $\nabla_{\theta}l^*(z_t, T_{an})$ , and retrieve fitted values  $\hat{y}_t$ . Then  $LM_{3n} = \frac{1}{n} \sum_{t=1}^n \hat{y}_t^2$ .

For MLE,  $g = \nabla_{\theta}l$  and the first regression is redundant, so that this procedure reduces to OLS.

Another form of the auxiliary regression for computing  $LM_{3n}$  is available in the case of non-linear instrumental variable regression. Consider the model  $y_t = h(x_t, \theta_0) + \varepsilon_t$  with  $E(\varepsilon_t | w_t) = 0$  and  $E(\varepsilon_t^2 | w_t) = \sigma^2$ , where  $w_t$  is a vector of instruments. Define  $z_t = (y_t, x_t, w_t)$  and  $g(z_t, \theta) = w_t[y_t - h(x_t, \theta)]$ . Then  $Eg(z, \theta_0) = 0$  and  $Eg(z, \theta_0)g(z, \theta_0)' = \sigma^2 Eww'$ . The GMM criterion  $Q_n(\theta)$  for this model is (28)

$$\left( \frac{1}{n} \sum_{t=1}^n w_t(y_t - h(x_t, \theta)) \right)' \left( \frac{1}{n} \sum_{t=1}^n w_t w_t' \right)^{-1} \left( \frac{1}{n} \sum_{t=1}^n w_t(y_t - h(x_t, \theta)) \right) / 2\sigma^2.$$

Optimization is not affected by the scalar  $\sigma^2$ .

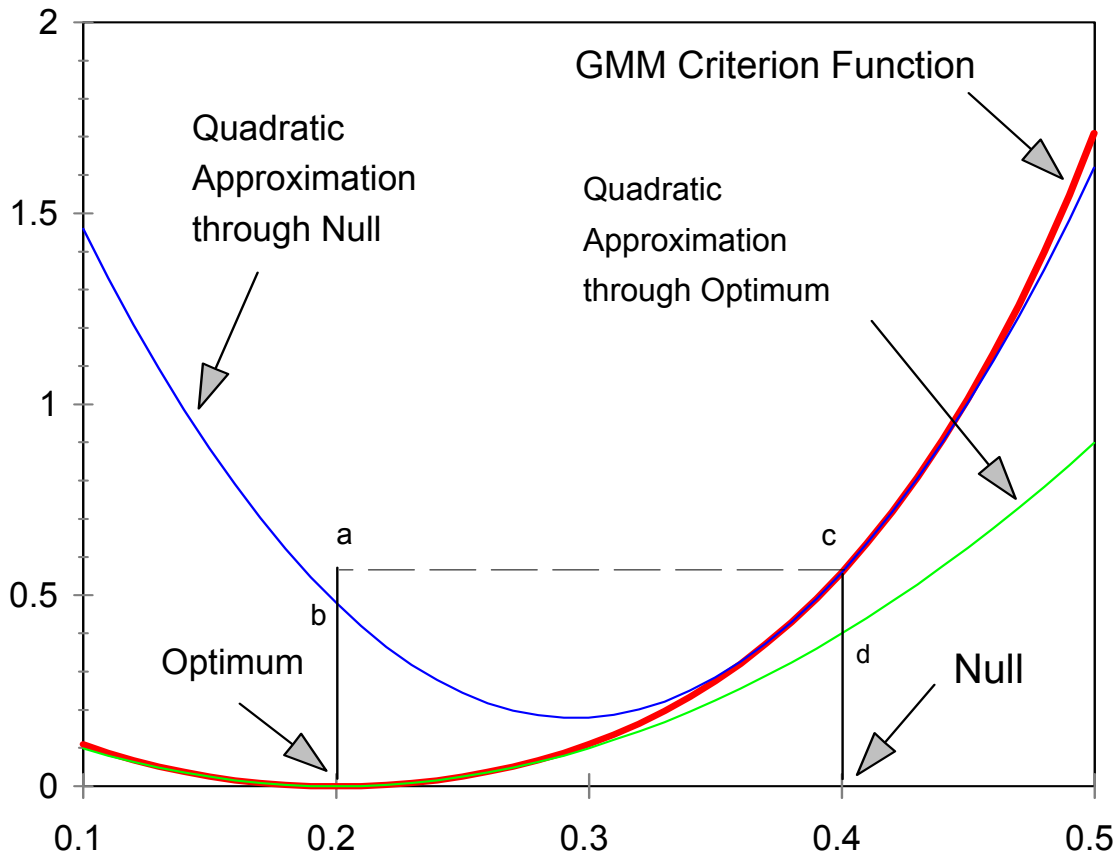
Consider the hypothesis  $a(\theta_0) = 0$ , and let  $T_{an}$  be the constrained GMM estimator. One can compute  $LM_{3n}$  by the following method:

- a. Regress  $\nabla_{\theta}h(x_t, T_{an})$  on  $w_t$ , and retrieve the fitted values  $\nabla_{\theta}\hat{h}_t$ .
- b. Regress the residual  $u_t = y_t - h(x_t, T_{an})$  on  $\nabla_{\theta}\hat{h}_t$ , and retrieve the fitted values  $\hat{u}_t$ .

Then  $LM_{3n} = n \sum_{t=1}^n \hat{u}_t^2 / \sum_{t=1}^n u_t^2 \equiv nR^2$ , with  $R^2$  the

*uncentered* multiple correlation coefficient. Note that this is not in general the same as the standard  $R^2$  produced by OLS programs, since the denominator of that definition is the sum of squared deviations of the dependent variable about its mean. When the dependent variable has mean zero, the centered and uncentered definitions coincide.

**The approach of the distance metric test is based on the difference between the values of the distance metric at the constrained and unconstrained estimates. It has a limiting chi-square distribution and is asymptotically equivalent to the other members of the trinity only for best GMM estimators. This estimator is particularly convenient when both the unconstrained and constrained estimators can be computed, and the estimation algorithm returns the goodness-of-fit statistics. In the case of linear or non-linear least squares, this is the familiar test statistic based on the sum of squared residuals from the constrained and unconstrained regressions.**



## TWO-STAGE GMM ESTIMATION

## ONE-STEP THEOREMS

## SPECIAL CASES

**Extremum estimators**

**Ordinary Least Squares**

**Simple hypotheses**



## TESTS FOR OVER-IDENTIFYING RESTRICTIONS

Consider the GMM estimator based on moments  $g(z_t, \theta)$ , where  $g$  is  $m \times 1$ ,  $\theta$  is  $k \times 1$ , and  $m > k$ , so there are *over-identifying moments*. The criterion

$$Q_n(\theta) = (1/2)g_n(\theta)' \Omega_n^{-1} g_n(\theta),$$

evaluated at its minimizing argument  $T_n$  for any  $\Omega_n \rightarrow_p \Omega$ , has the property that  $2nQ_n \equiv 2nQ_n(T_n) \rightarrow_d \chi^2(m-k)$  under the null hypothesis that  $Eg(z, \theta_0) = 0$ .

The test for overidentifying restrictions can be recast as a LM test by artificially embedding the original model in a richer model. Partition the moments

$$g(z, \theta) = \begin{bmatrix} g^1(z, \theta) \\ g^2(z, \theta) \end{bmatrix},$$

where  $g^1$  is  $k \times 1$  with  $G_1 = E \nabla_{\theta} g^1(z, \theta_0)$  of rank  $k$ , and  $g^2$  is  $(m-k) \times 1$  with  $G_2 = E \nabla_{\theta} g^2(z, \theta_0)$ . Embed this in the model

$$g^*(z, \theta, \psi) = \begin{bmatrix} g^1(z, \theta) \\ g^2(z, \theta) + \psi \end{bmatrix}$$

where  $\psi$  is a  $(m-k)$  vector of additional parameters. The first-order-condition for GMM estimation of this expanded model is

$$\begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} G_{1n} & G_{2n} \\ 0 & I_{m-k} \end{bmatrix} \begin{bmatrix} \Omega_n & 0 \\ 0 & I_{m-k} \end{bmatrix} \begin{bmatrix} g_n(T_{an}) \\ g_n(T_{an}) - \psi_n \end{bmatrix}$$

The second block of conditions are satisfied by  $\psi_n = g_n(T_{an})$ , no matter what  $T_{an}$ , so  $T_{an}$  is determined by  $0 = G_n \Omega_n g_n(T_{an})$ . This is simply the estimator obtained from the first block of moments, and coincides with the earlier definition of  $T_{an}$ . Thus, *unconstrained* estimation of the *expanded* model coincides with *restricted* estimation of the original model. Next consider GMM estimation of the expanded model subject to  $H_0: \psi = 0$ . This constrained estimation obviously coincides with GMM estimation using all moments in the original model, and yields  $T_n$ . Thus, *constrained* estimation of the *expanded* model coincides with *unrestricted* estimation of the original model.

The Distance Metric test statistic for the constraint  $\psi = 0$  in the expanded model is  $DM_n = 2n[Q_n(T_n, 0) - Q_n(T_n, \psi_n)] \equiv 2nQ_n(T_n)$ , where  $Q_n$  denotes the criterion as a function of the expanded parameter list. One has  $Q_n(T_n, 0) \equiv Q_n(T_n)$  from the coincidence of the constrained expanded model estimator and the unrestricted original model estimator, and one has  $Q_n(T_{an}, \psi_n) = 0$  since the number of moments equals the number of parameters. Then, the test statistic  $2nQ_n(T_n)$  for overidentifying restrictions is identical to a distance metric test in the expanded model, and hence asymptotically equivalent to any of the trinity of tests for  $H_0: \psi = 0$  in the expanded model.

**We give four examples of econometric problems that can be formulated as tests for over-identifying restrictions:**

**Example 1. If  $y = x\beta + \varepsilon$  with  $E(\varepsilon|x) = 0$ ,  $E(\varepsilon^2|x) = \sigma^2$ , then the moments**

$$g^1(z, \beta) = \begin{bmatrix} x(y - x\beta) \\ (y - x\beta)^2 - \sigma^2 \end{bmatrix}$$

**can be used to estimate  $\beta$  and  $\sigma^2$ . If  $\varepsilon$  is normal, then GMM estimators based on  $g^1$  are MLE. Normality can be tested via the additional moments that give skewness and kurtosis,**

$$g^2(x, \beta) = \begin{bmatrix} (y - x\beta)^3 / \sigma^3 \\ (y - x\beta)^4 / \sigma^4 - 3 \end{bmatrix}.$$

**GMM estimators based on all the moments  $g$  are again MLE**

**Example 2.** In the linear model  $y = \mathbf{x}\mathbf{b} + \boldsymbol{\varepsilon}$  with  $E(\boldsymbol{\varepsilon}|\mathbf{x}) = \mathbf{0}$  and  $E(\boldsymbol{\varepsilon}_t \boldsymbol{\varepsilon}_s | \mathbf{x}) = 0$  for  $t \neq s$ , but with possible heteroskedasticity of unknown form, one gets the OLS estimates  $\mathbf{b}$  of  $\boldsymbol{\beta}$  and  $V(\mathbf{b}) = s^2(\mathbf{X}'\mathbf{X})^{-1}$  under the null hypothesis of homoskedasticity. A test for homoskedasticity can be based on the population moments  $\mathbf{0} = E \text{vecu}[\mathbf{x}'\mathbf{x}(\boldsymbol{\varepsilon}^2 - \sigma^2)]$ , where "vecu" means the vector formed from the upper triangle of the array. The sample value of this moment vector is

$$\text{vecu} \left[ \frac{1}{n} \sum_{t=1}^n \mathbf{x}_t' \mathbf{x}_t \left( (y_t - \mathbf{x}_t \boldsymbol{\beta})^2 - s^2 \right) \right],$$

the difference between the White robust estimator and the standard OLS estimator of  $\text{vecu}[\mathbf{X}'\boldsymbol{\Omega}\mathbf{X}]$ .

**Example 3.** If  $l(z, \theta)$  is the log likelihood of an observation, and  $T_n$  is the MLE, then an additional moment condition that should hold if the model is specified correctly is the information matrix equality

$$\mathbf{0} = \mathbf{E} \nabla_{\theta\theta} l(z, \theta_o) + \mathbf{E} \nabla_{\theta} l(z, \theta_o) \nabla_{\theta} l(z, \theta_o)'$$

The sample analog is White's information matrix test, which then can be interpreted as a GMM test for over-identifying restrictions.

**Example 4.** In the nonlinear model  $y = h(x, \theta) + \varepsilon$  with  $E(\varepsilon|x) = 0$ , and  $T_n$  a GMM estimator based on moments  $w(x)(y-h(x, \theta))$ , where  $w(x)$  is some vector of functions of  $x$ , suppose one is interested in testing the stronger assumption that  $\varepsilon$  is *independent* of  $x$ . A necessary and sufficient condition for independence is  $E[w(x) - Ew(x)]f(y - h(x, \theta_0)) = 0$  for every function  $f$  and vector of functions  $w$  for which the moments exist. A specification test can be based on a selection of such moments.

## SPECIFICATION TESTS IN LINEAR MODELS

GMM tests for over-identifying restrictions have particularly convenient forms in linear models. Three standard specification tests will be shown to have this interpretation. Let  $P_X = X(X'X)^-X$  denote the *projection matrix* from  $\mathbb{R}^n$  onto the linear subspace  $X$  spanned by a  $n \times p$  array  $X$ ; note that it is idempotent. (We use a Moore-Penrose generalized inverse in the definition of  $P_X$  to handle the possibility that  $X$  is less than full rank.) Let  $Q_X = I - P_X$  denote the projection matrix onto the linear subspace orthogonal to  $X$ . If  $X$  is a subspace generated by an array  $X$  and  $W$  is a subspace generated by an array  $W = [X \ Z]$  that contains  $X$ , then  $P_X P_W = P_W P_X = P_X$  and  $Q_X P_W = P_W - P_X$ .

*Omitted Variables Test:* Consider the regression model  $y = X\beta + \varepsilon$ , where  $y$  is  $n \times 1$ ,  $X$  is  $n \times k$ ,  $E(\varepsilon|X) = 0$ , and  $E(\varepsilon\varepsilon'|X) = \sigma^2 I$ . Suppose one has the hypothesis  $H_0: \beta_1 = 0$ , where  $\beta_1$  is a  $p \times 1$  subvector of  $\beta$ , and let  $X^*$  denote the  $n \times (k-p)$  array of variables whose coefficients are not constrained under the null hypothesis. Define  $u = y - Xb$  to be the residual associated with an estimator  $b$  of  $\beta$ . The GMM criterion is then  $2nQ = u'X(X'X)^-1X'u/\sigma^2$ .

The *projection matrix*  $P_X \equiv X(X'X)^{-1}X'$  that appears in the center of this criterion can obviously be decomposed as  $P_X \equiv P_{X^*} + (P_X - P_{X^*})$ . Under  $H_0$ ,  $u = y - X_2b_2$  and  $X'u$  can be interpreted as  $k = p + q$  over-identifying moments for the  $q$  parameters  $\beta_2$ . Then, the GMM test statistic for over-identifying restrictions is the minimum value  $2nQ_n^*$  in  $b_2$  of  $u'P_Xu/\sigma^2$ . But  $P_Xu = P_{X^*}u + (P_X - P_{X^*})y$  and  $\min_{b_2} u'$

$P_{X^*}u = 0$  (at the OLS estimator under  $H_0$  that makes  $u$  orthogonal to  $X_2$ ). Then  $2nQ_n = y'(P_X - P_{X^*})y/\sigma^2$ . The unknown variance  $\sigma^2$  in this formula can be replaced by any consistent estimator  $s^2$ , in particular, the estimated variance of the disturbance from either the restricted or the unrestricted regression, without altering the asymptotic distribution, which is  $\chi^2(q)$  under the null hypothesis.

The statistic  $2nQ_n$  has three alternative interpretations. First,

$$2nQ_n = y'P_Xy/\sigma^2 - y'P_{X^*}y/\sigma^2 = \frac{SSR_{X_2} - SSR_X}{\sigma^2},$$

which is the difference of the sum of squared residuals from the restricted regression under  $H_0$  and from the unrestricted regression, normalized by  $\sigma^2$ . This is a large-sample version of the usual finite-sample F-test for  $H_0$ .



Second, note that the fitted value of the dependent variable from the restricted regression is  $\hat{y}_o = P_{X^*} y$ , and from the unrestricted regression is  $\hat{y}_u = P_X y$ , so that

$$2nQ_n = (\hat{y}_o' \hat{y}_o - \hat{y}_u' \hat{y}_u) / \sigma^2 = (\hat{y}_o - \hat{y}_u)' (\hat{y}_o - \hat{y}_u) / \sigma^2 = \|\hat{y}_o - \hat{y}_u\|^2 / \sigma^2.$$

Then, the statistic is calculated from the distance between the fitted values of the dependent variable with and without  $H_0$  imposed. Note that it can be computed from fitted values without any covariance matrix calculation.

Third, let  $b_o$  denote the GMM estimator restricted by  $H_0$  and  $b_u$  denote the unrestricted GMM estimator. Then,  $b_o$  consists of the OLS estimator for  $\beta_2$  and the hypothesized value 0 for  $\beta_1$ , while  $b_u$  is the OLS estimator for the full parameter vector. Note that  $\hat{y}_o = Xb_o$  and  $\hat{y}_u = Xb_u$ , so that  $\hat{y}_o - \hat{y}_u = X(b_o - b_u)$ . Then

$$\begin{aligned} 2nQ_n &= (b_o - b_u)' (X'X / \sigma^2) (b_o - b_u) \\ &= (b_o - b_u)' V(b_u)^{-1} (b_o - b_u). \end{aligned}$$

This is the Wald statistic  $W_{3n}$ . From the equivalent form  $W_{2n}$  of the Wald statistic, this can also be written as a quadratic form  $2nQ_n = b_{1,u}' V(b_{1,u})^{-1} b_{1,u}$ , where  $b_{1,u}$  is the subvector of unrestricted estimates for the parameters that are zero under the null hypothesis.